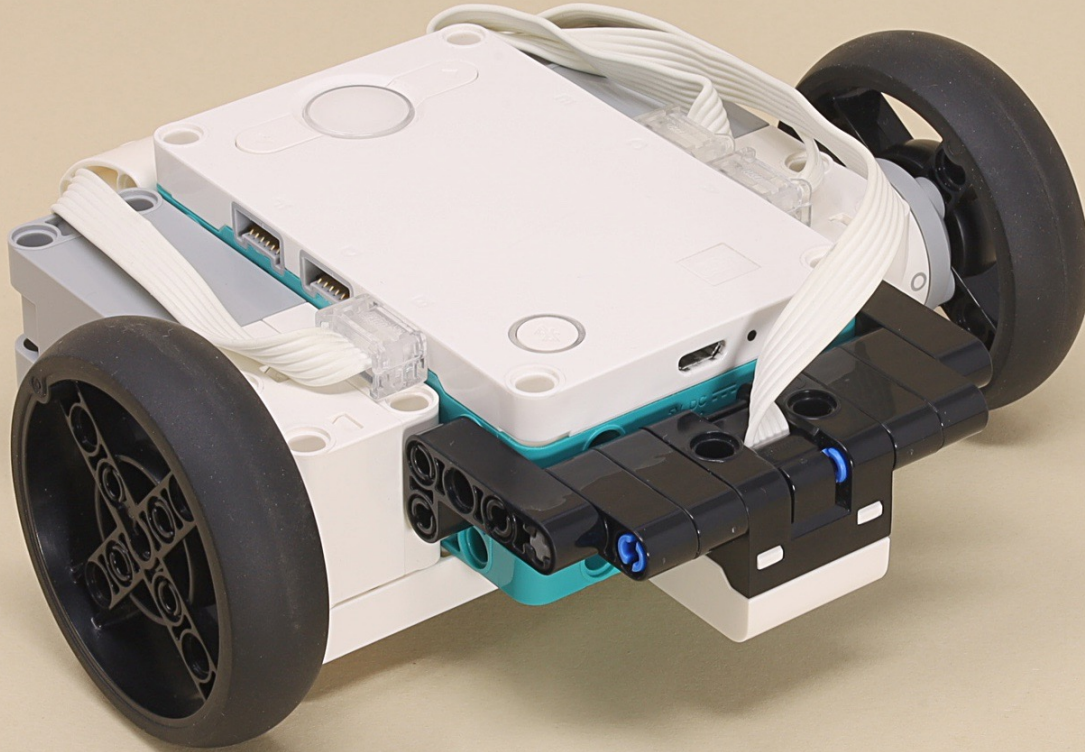


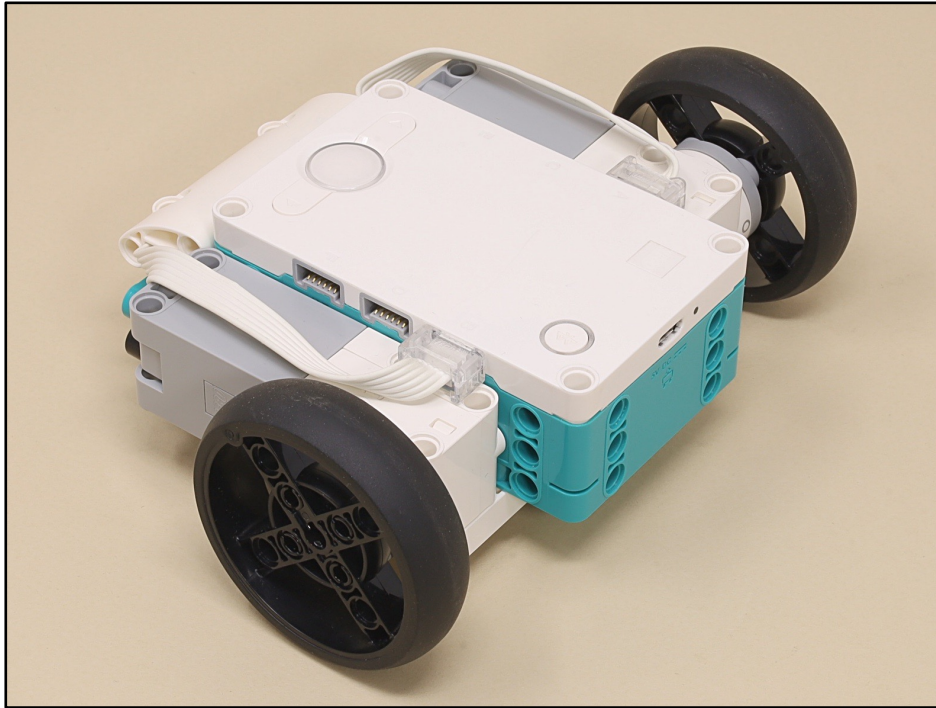
# Line Follower



Scroll for  
building  
instructions



Start by building:



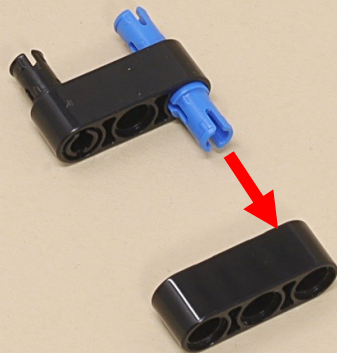
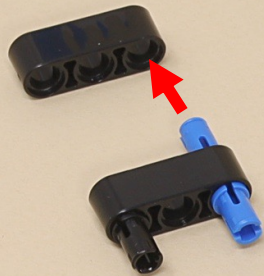
Classic Bot

...then continue here to complete the Line Follower



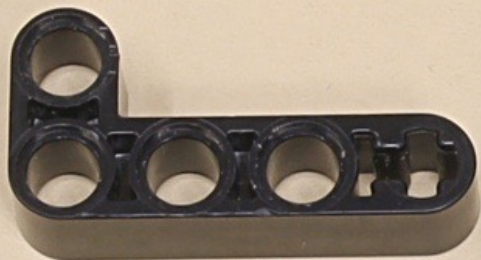






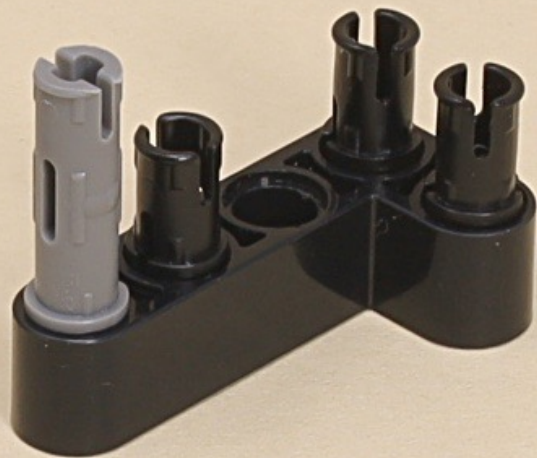
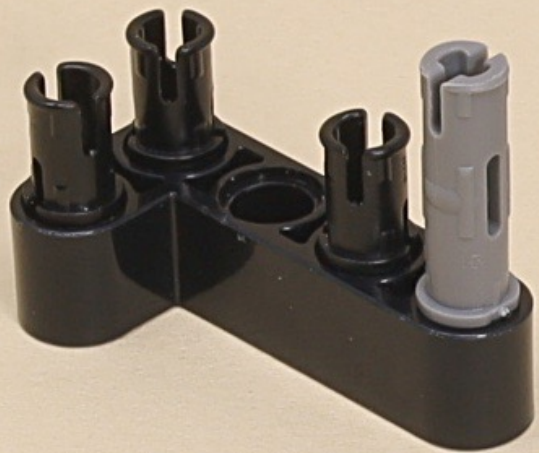




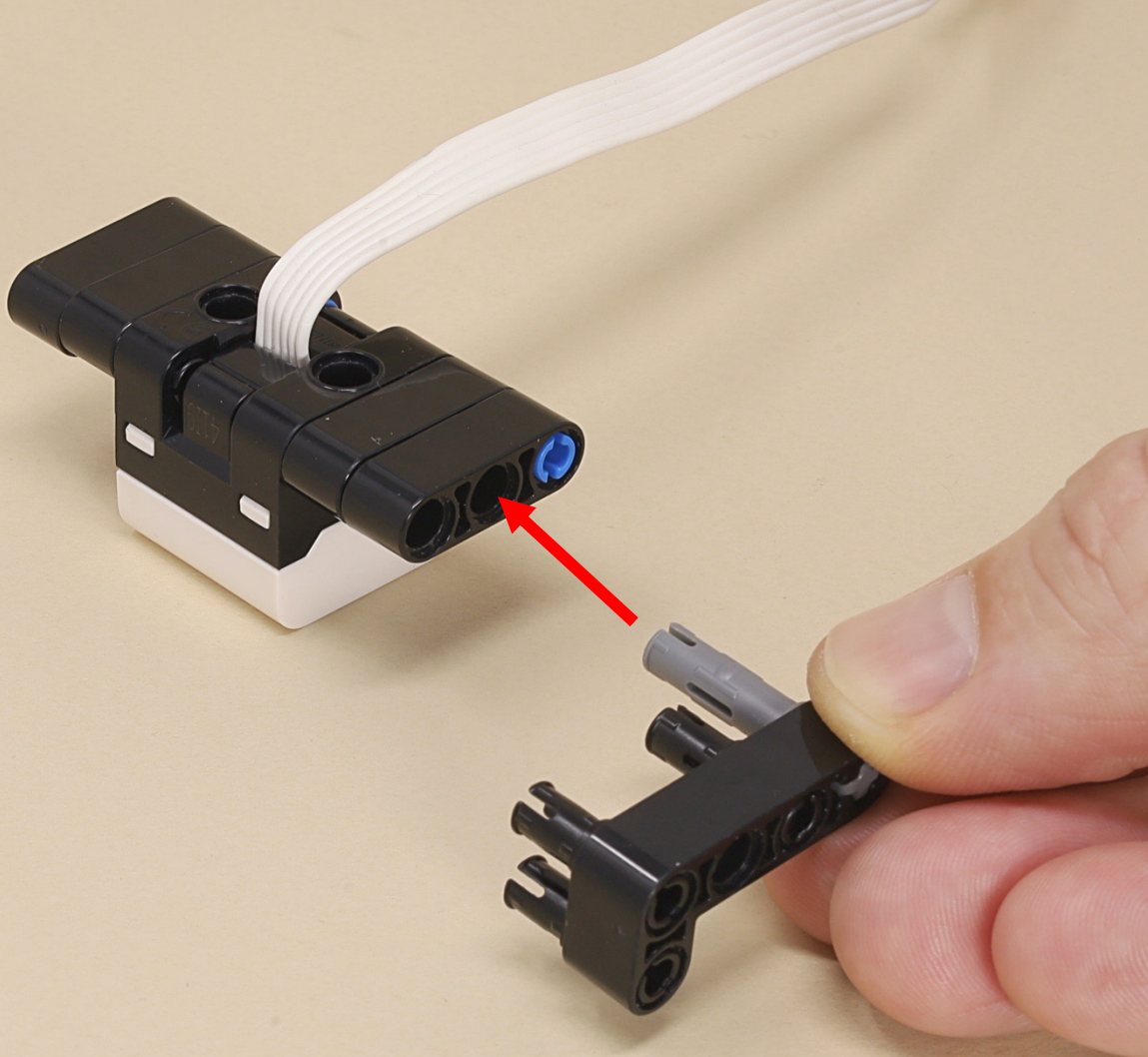
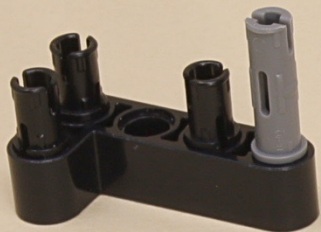


**(6 x)**

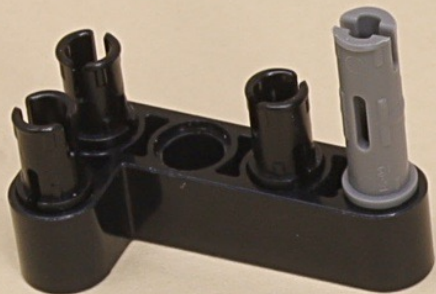


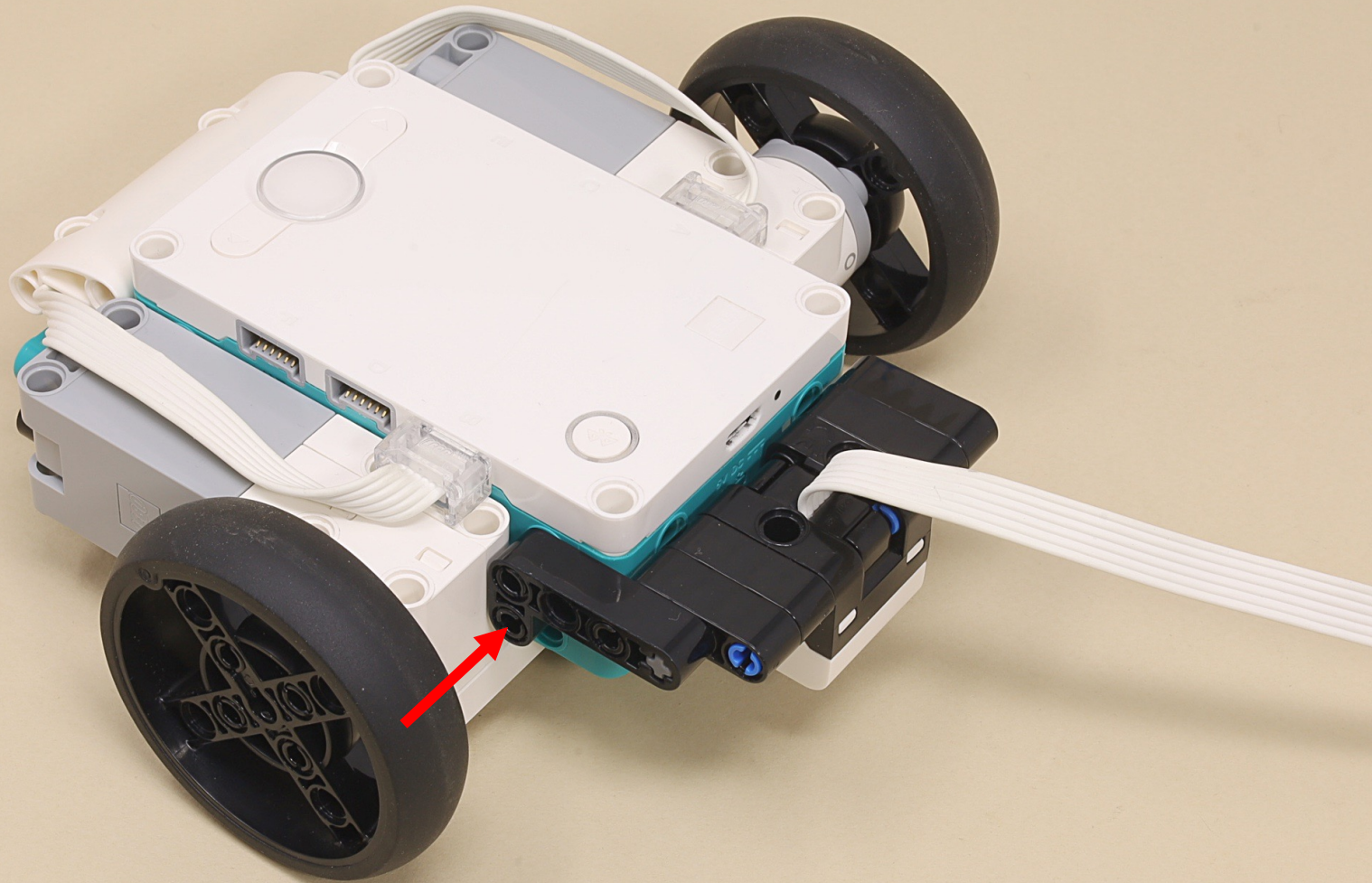




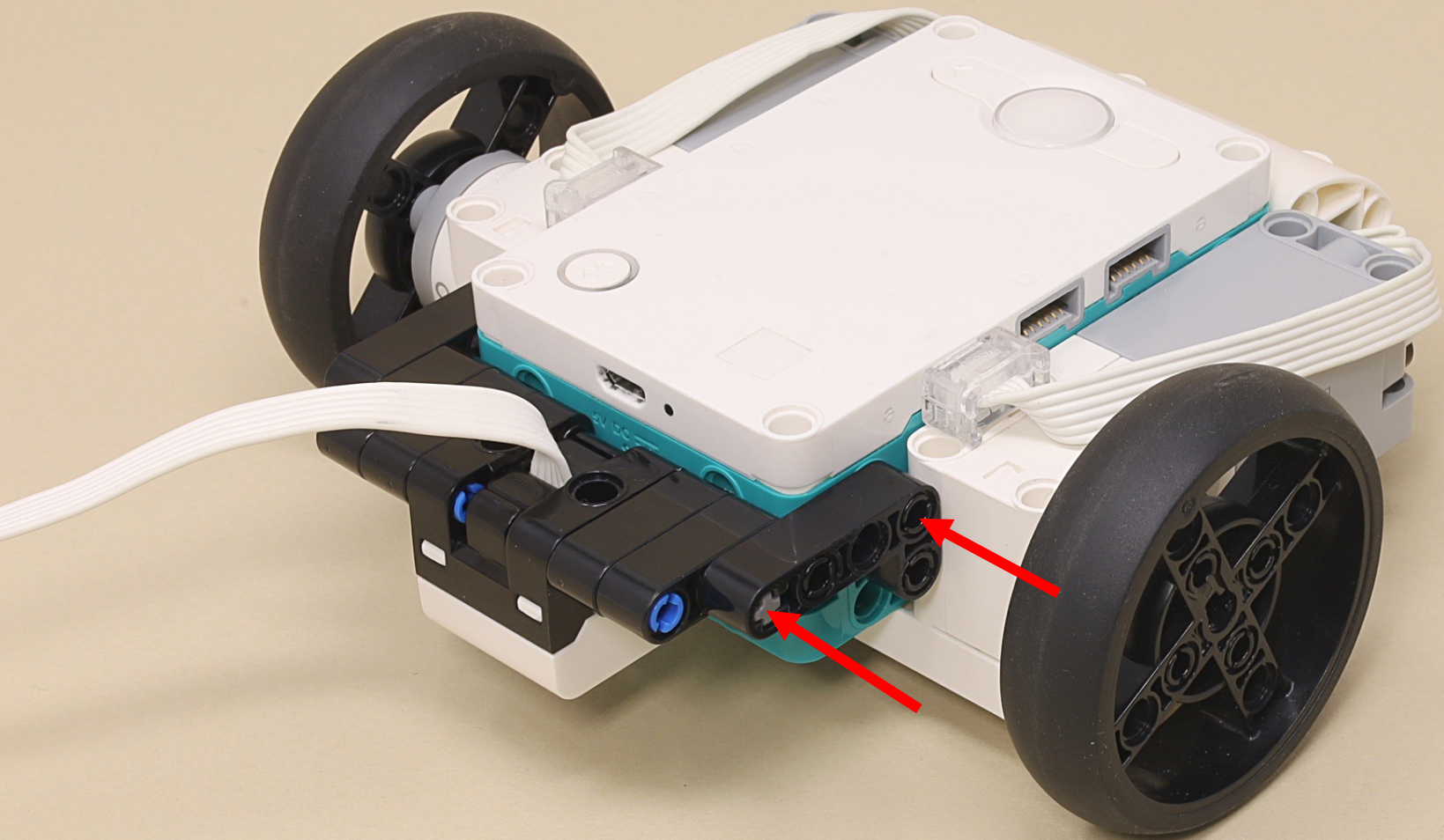




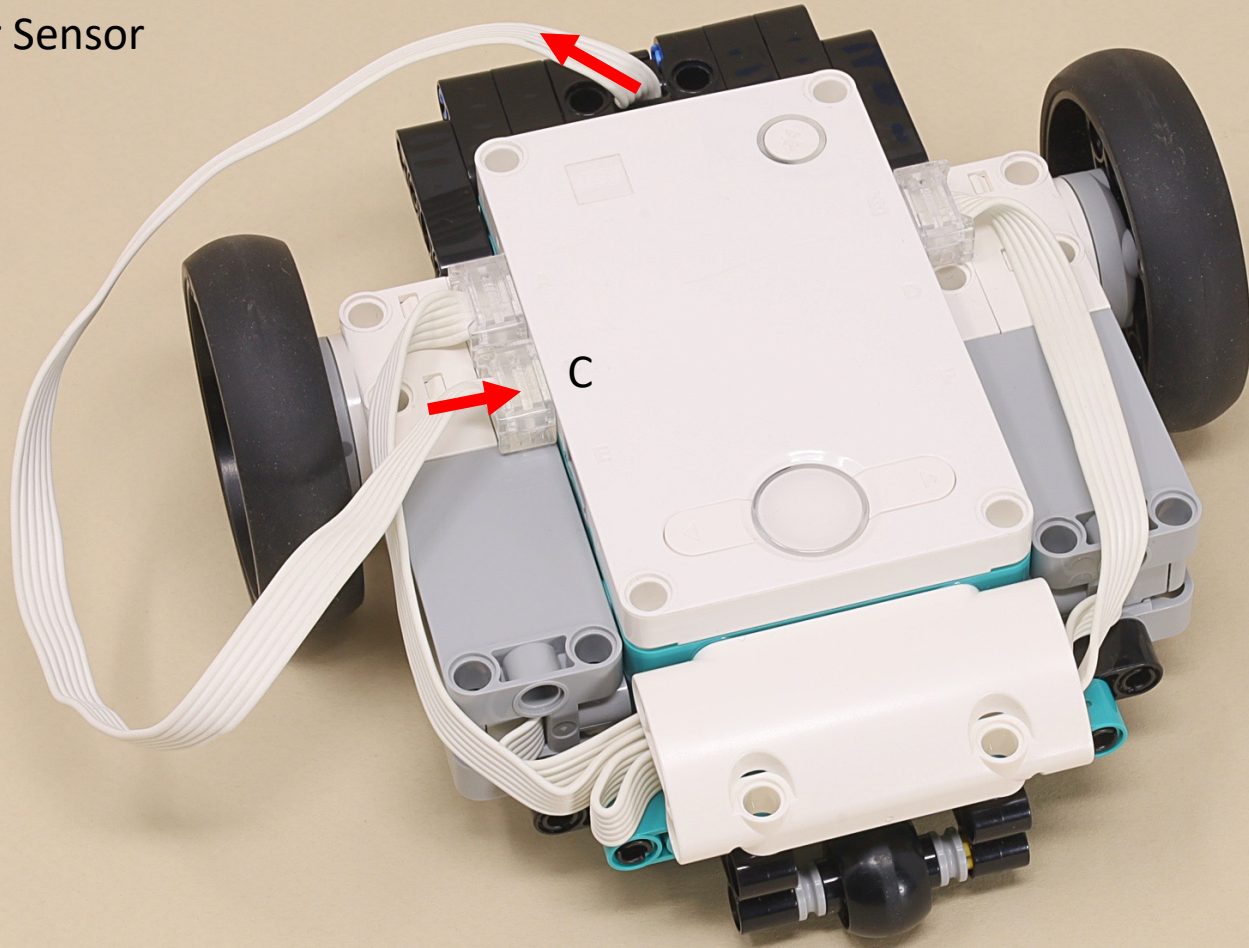






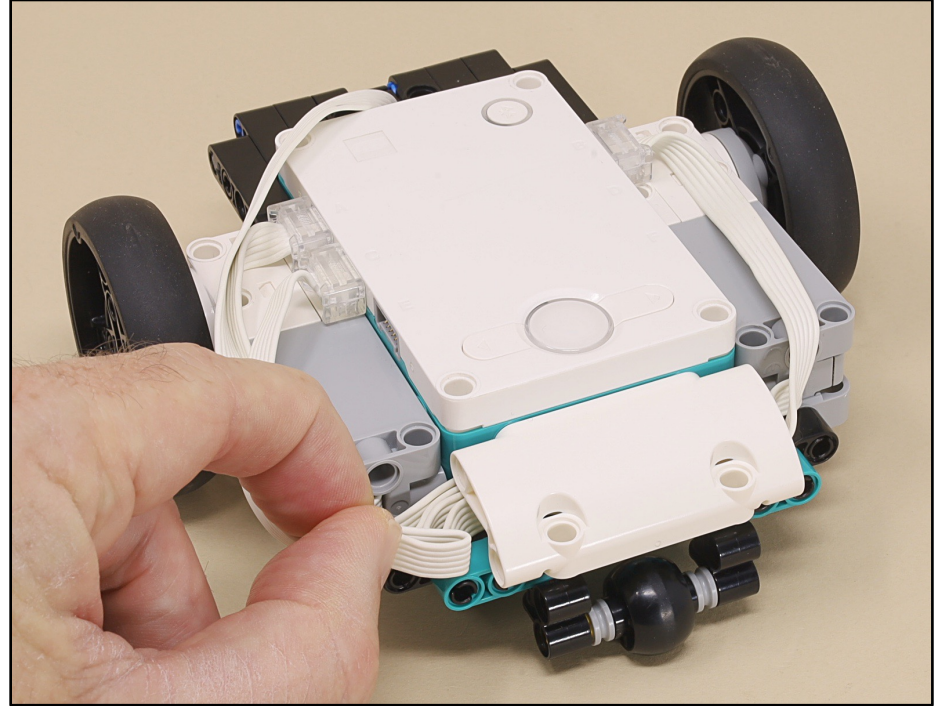
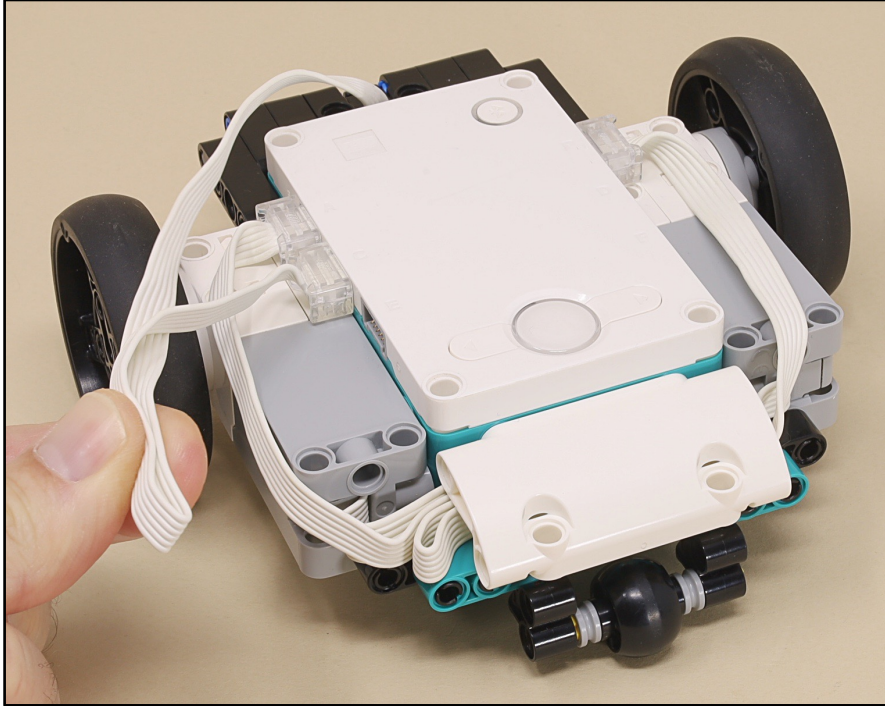


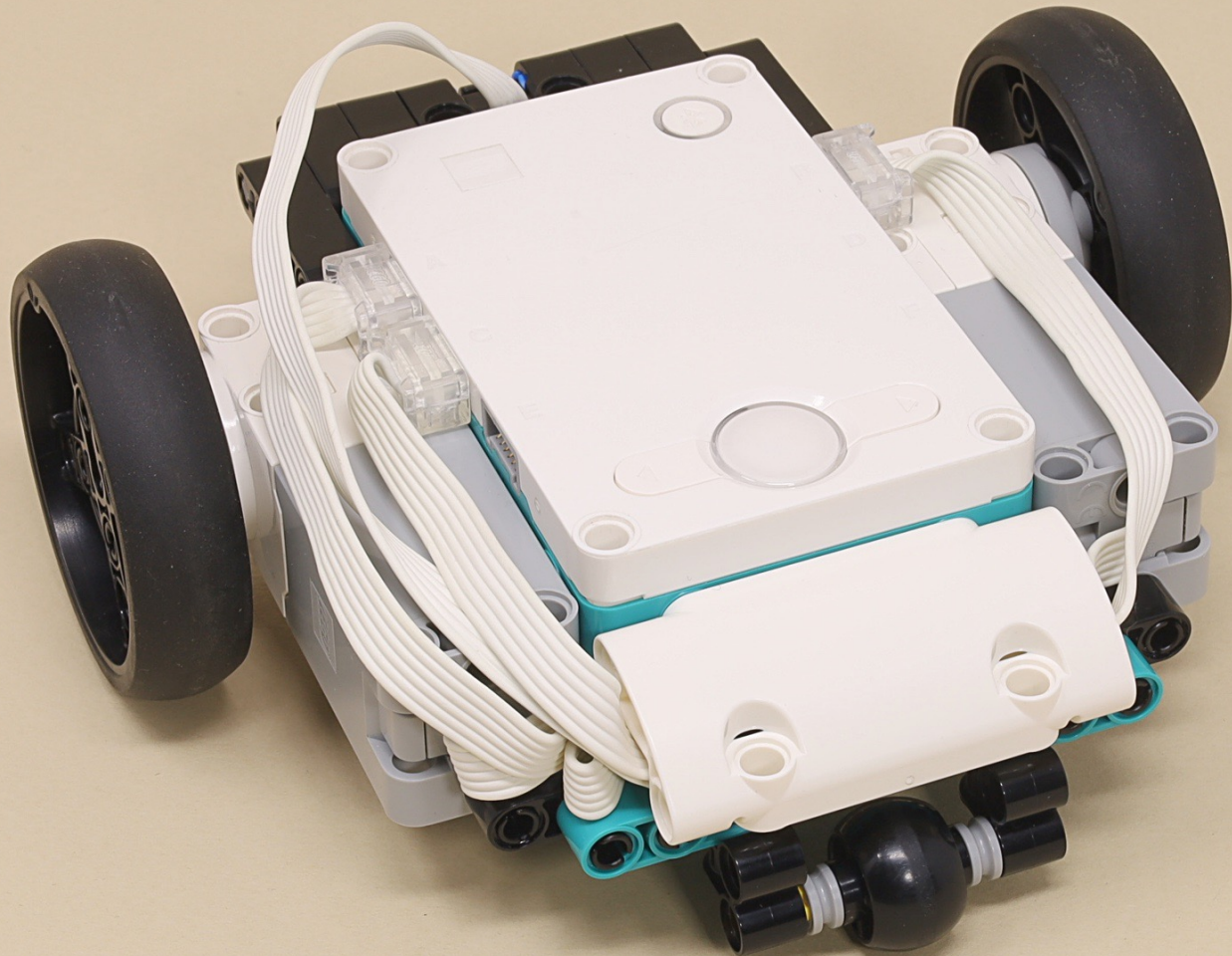
C = Color Sensor





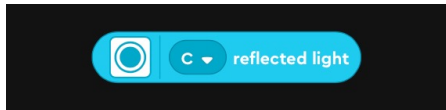
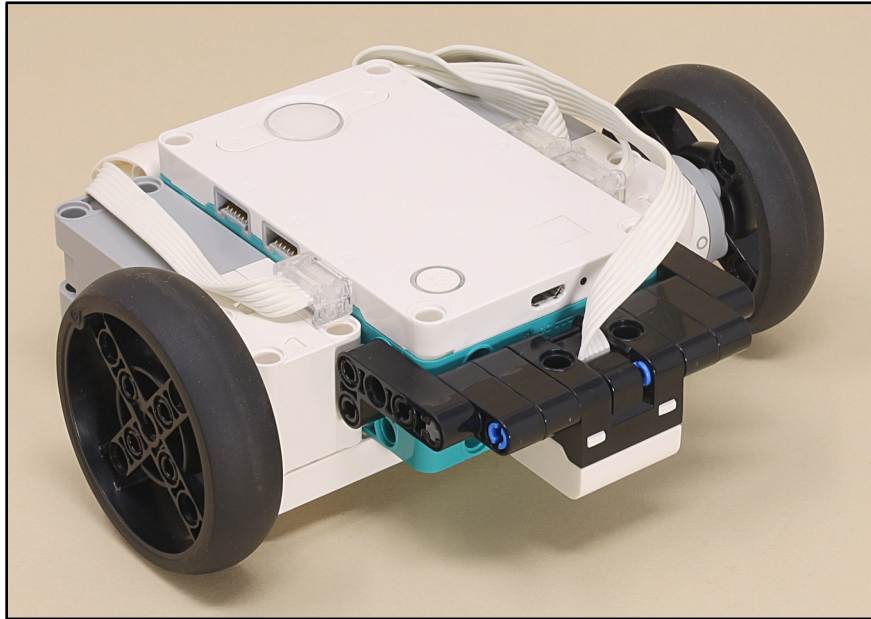
You can fold and stuff the extra wire length into this space.







Note: The Color sensor at this height off the ground seems to work well for using Reflected Light readings in the program, which is good for line following.



If you want to try sensing Color readings on the ground instead of Reflected Light, the sensor needs to be much closer to the ground. Try this sensor mount for that:

